

Meshless Polyharmonic Div-Curl Reconstruction

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Abstract. In this paper, we will discuss the meshless polyharmonic reconstruction of vector fields from scattered data, possibly, contaminated by noise. We give an explicit solution of the problem. After some theoretical framework, we discuss some numerical aspect arising in the problems related to the reconstruction of vector fields.

Key words: approximation theory, meshless approximation methods, radial basis functions

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1. Introduction

Vector field reconstruction is a problem arising in many scientific applications. These include, for example, fluid mechanic, electromagnetic, meteorology and optic flow analysis. When considering the approximation of vector fields, a key problem is how to correlate its components. It has been observed, particularly for meteorological problems, that if no inter-component correlation is assumed the approximating field may give unrealistic results. In this paper, we present a brief discussion on the reconstruction of vector fields from scattered data points by using polyharmonic meshless approximation. The theory of polyharmonic div-curl reconstruction was developed in a general framework based upon earlier results on generalized pseudo-polyharmonic approximation [1].

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2. The functional space

Let $n, m \in \mathbb{N}^* := \mathbb{N} \setminus \{0\}$ with $n \geq 2$, and consider the space

$$X^m(\mathbb{R}^n; \mathbb{R}^n) = \left\{ u = (u_1, \dots, u_n)^T \in \mathcal{D}'(\mathbb{R}^n; \mathbb{R}^n) : \right. \\ \left. \forall \alpha \in \mathbb{Z}_+^n, |\alpha| = m, \partial^\alpha u_i \in L^2(\mathbb{R}^n), i = 1, \dots, n \right\}, \quad (2.1)$$

where $\mathcal{D}'(\mathbb{R}^n; \mathbb{R}^n)$ is the space of the vector-valued distributions on \mathbb{R}^n , and the notation u^T stands for the transpose of u . We assume that

$$m > \frac{n}{2}. \quad (2.2)$$

The space $X^m(\mathbb{R}^n; \mathbb{R}^n)$ is equipped with the following semi-scalar product and its associated semi-norm

$$(u|v)_m = \sum_{|\alpha|=m} \frac{m!}{\alpha!} \int_{\mathbb{R}^n} \partial^\alpha u^T(\xi) \partial^\alpha v(\xi) d\xi, \quad |u|_m = \sqrt{(u|u)_m}. \quad (2.3)$$

The null space associated to the semi-scalar product is the space, denoted by $\Pi_{m-1}(\mathbb{R}^n; \mathbb{R}^n)$ of vector-valued polynomials of n -variables with degree $\leq m-1$.

Let N be a nonnegative integer and suppose we are given a collection of N distinct points x_1, \dots, x_N in \mathbb{R}^n , such that the set $\Omega_N = \{x_1, \dots, x_N\}$ contains a $\Pi_{m-1}(\mathbb{R}^n)$ -unisolvent subset. We recall that a set Ω is $\Pi_{m-1}(\mathbb{R}^n)$ -unisolvent if any polynomial in $\Pi_{m-1}(\mathbb{R}^n)$ which vanishes on Ω is identically zero. We consider the operator $L : X^{m,s}(\mathbb{R}^n; \mathbb{R}^n) \longrightarrow \mathbb{R}^{N \times n}$ given for $u = (u_1, \dots, u_n)^T$ by

$$Lu = \begin{pmatrix} u_1(x_1) & \dots & u_n(x_1) \\ \vdots & \ddots & \vdots \\ u_1(x_N) & \dots & u_n(x_N) \end{pmatrix}. \quad (2.4)$$

The space $X^m(\mathbb{R}^n; \mathbb{R}^n)$ is now equipped with the scalar product associated to the operator L and defined by

$$(u|v)_{L,m} = (u|v)_{L,m} + \langle Lu|Lv \rangle_{N \times n}. \quad (2.5)$$

The associated norm is denoted by $\|u\|_{L,m} = \sqrt{(u|u)_{L,m}}$. Here the notation $\langle \cdot | \cdot \rangle_{N \times n}$ stands for the Frobenius scalar product $\langle z|z' \rangle_{N \times n} = \text{trace}(z^T z')$. Its associated norm is denoted by $\|\cdot\|_{N \times n}$ in $\mathbb{R}^{N \times n}$. The following proposition gives some topological properties of the space $X^m(\mathbb{R}^n; \mathbb{R}^n)$ equipped with the scalar product (2.5) and its associated norm.

Proposition 1. *The space $X^m(\mathbb{R}^n; \mathbb{R}^n)$ endowed with the scalar product $(\cdot|\cdot)_{L,m}$ is a Hilbert space. The following continuous inclusions hold, for all integer k such that $k < m - n/2$,*

$$X^m(\mathbb{R}^n; \mathbb{R}^n) \hookrightarrow \mathcal{S}'(\mathbb{R}^n; \mathbb{R}^n), \quad X^m(\mathbb{R}^n; \mathbb{R}^n) \hookrightarrow \mathcal{C}^k(\mathbb{R}^n; \mathbb{R}^n).$$

Furthermore, the space $\mathcal{D}'(\mathbb{R}^n; \mathbb{R}^n) + \Pi_{m-1}(\mathbb{R}^n; \mathbb{R}^n)$ is dense in $X^m(\mathbb{R}^n; \mathbb{R}^n)$.

Proof. See [1].

3. Polyharmonic div-curl approximation

The div and curl operators are defined by

$$\operatorname{div} u = \nabla^T \cdot u = \sum_{i=1}^n \partial_i u_i, \quad \operatorname{curl} u = \nabla \cdot u^T - (\nabla \cdot u^T)^T = (\partial_i u_j - \partial_j u_i)_{1 \leq i, j \leq n},$$

where $\nabla = (\partial_1, \dots, \partial_n)^T$ stands for the gradient operator and $u = (u_1, \dots, u_n)^T$ is a vector-valued distribution. The general definition of the curl is classical in multidimensional harmonic analysis, see [3, 6]. Let $\rho > 0$ denote a positive real parameter. We consider the bilinear forms D_m , R_m and M_m^ρ given by

$$\begin{aligned} D_m(u, v) &= \sum_{|\alpha|=m-1} \frac{(m-1)!}{\alpha!} \int_{\mathbb{R}^n} \partial^\alpha (\operatorname{div} u)(\xi) \partial^\alpha (\operatorname{div} v)(\xi) d\xi, \\ R_m(u, v) &= \frac{1}{2} \sum_{|\alpha|=m-1} \frac{(m-1)!}{\alpha!} \int_{\mathbb{R}^n} \langle \partial^\alpha (\operatorname{curl} u)(\xi) \mid \partial^\alpha (\operatorname{curl} v)(\xi) \rangle_{n \times n} d\xi, \\ M_m^\rho(u, v) &= \rho D_m(u, v) + R_m(u, v). \end{aligned}$$

The quadratic forms associated to D_m , R_m and M_m^ρ are called the div-energy, the curl-energy and the div-curl energy, respectively.

Let $Z \in \mathbb{R}^{N \times n}$ be a $N \times n$ matrix, $\rho > 0$, and $\lambda \geq 0$ and consider the following approximation problem:

$$\min_{v \in I_\lambda^m(Z)} \left(M_m^\rho(v, v) + \lambda \left\| L[v] - Z \right\|_{N \times n}^2 \right), \quad (3.1)$$

where $I_0^m(Z) = \{v \in X^m(\mathbb{R}^n; \mathbb{R}^n) : L(v) = Z\}$ and $I_\lambda^m(Z) = X^m(\mathbb{R}^n; \mathbb{R}^n)$ for $\lambda > 0$.

We have the following

Theorem 2. *For all $Z \in \mathbb{R}^{N \times n}$, $\rho > 0$ and $\lambda \geq 0$. The problem (3.1) has a unique solution, denoted by σ_λ . The solution σ_λ is the unique element in $X^m(\mathbb{R}^n; \mathbb{R}^n)$ characterized by*

$$M_m^\rho(\sigma_0, v) = 0, \quad \forall v \in \ker(L), \quad (3.2)$$

for $\lambda = 0$, and for $\lambda > 0$:

$$M_m^\rho(\sigma_\lambda, v) + \lambda \langle L[\sigma_\lambda] - Z \mid L[v] \rangle_{N \times n} = 0, \quad \forall v \in X^m(\mathbb{R}^n; \mathbb{R}^n). \quad (3.3)$$

Proof. The results are obtained from some arguments using the variational spline theory, see [1].

Let us consider the function K_m , see [2, 5], defined by

$$K_m(x) = \begin{cases} c_{1,m} \|x\|^{2m-n} \log(\|x\|) & \text{if } m - n/2 \in \mathbb{N}^*, \\ c_{2,m} \|x\|^{2m-n} & \text{if } m - n/2 \notin \mathbb{N}^*, \end{cases}$$

The values of the constants $c_{1,m}$ and $c_{2,m}$ are such that the function K_m satisfies the following relation $\Delta^m K_m = \delta$, where δ is the Dirac measure at the origin. For $\rho > 0$, we introduce the matrix-function F_m^ρ defined by

$$F_{m,s}^\rho = \left(-\delta_{l,k} \Delta K_{m+1} + \left(1 - \frac{1}{\rho}\right) \partial_{l,k}^2 K_{m+1} \right)_{1 \leq l, k \leq n},$$

where the notation $\delta_{l,k}$ stands for the Kronecker symbol and $\partial_{l,k}^2$ stands for the second partial derivative.

Let $d = (m+n-1)!/(n!(m-1)!)$ be the dimension and (q_1, \dots, q_d) be a basis of the scalar space $\Pi_{m-1}(\mathbb{R}^n)$, respectively. The following theorem gives an explicit expression of the unique solution σ_λ of Problem (3.1):

Theorem 3. *There is a unique vector-measure ω_λ of the form*

$$\omega_\lambda = \left(\sum_{i=1}^N \alpha_{i,1}^{(\lambda)} \delta_{x_i}, \dots, \sum_{i=1}^N \alpha_{i,n}^{(\lambda)} \delta_{x_i} \right)^T,$$

*orthogonal to the space $\Pi_{m-1}(\mathbb{R}^n; \mathbb{R}^n)$, such that $\sigma_\lambda - F_{m,s}^\rho * \omega_\lambda \in \Pi_{m-1}(\mathbb{R}^n; \mathbb{R}^n)$. Thus, there are unique vectors $V_{1,\lambda}, \dots, V_{N,\lambda} \in \mathbb{R}^n$ and $W_{1,\lambda}, \dots, W_{d,\lambda} \in \mathbb{R}^n$ such that the unique solution σ_λ of Problem (3.1) is explicitly given by*

$$\sigma_\lambda(x) = \sum_{i=1}^N F_{m,s}^\rho(x - x_i) V_{i,\lambda} + \sum_{j=1}^d q_j(x) W_{j,\lambda}, \quad \forall x \in \mathbb{R}^n,$$

with the orthogonality conditions $\sum_{i=1}^N q_j(x_i) V_{i,\lambda} = 0$, for $j = 1, \dots, d$.

Proof. The result is a consequence of Theorem 2, see [1].

4. Numerical example

In Figure 1, we give an original vector field and the pseudo-polyharmonic vector fields approximating the original vector field for $\rho = 0.4$, $\lambda = 0$ and for a small value $N = 10$ and a large value $N = 1000$ of the scattered data points. We point out that when N becomes large the reconstructed vector field is similar to the original vector field. The computed relative error was $R_e \simeq 1.5713 \times 10^{-1}$ for $N = 10$ and $R_e \simeq 1.0403 \times 10^{-4}$ for $N = 1000$.

References

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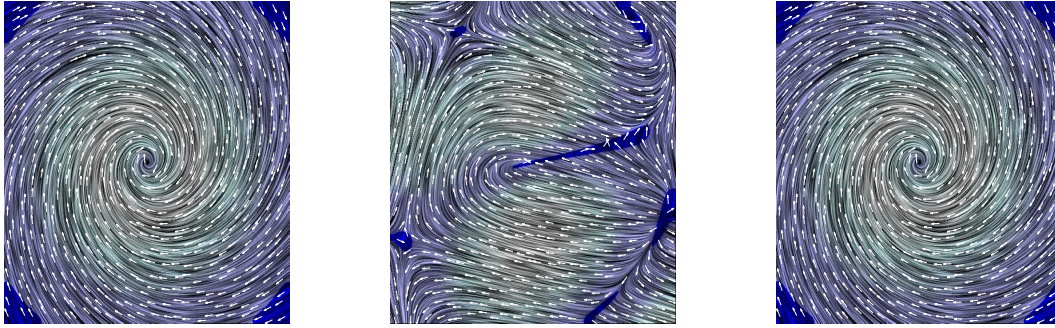


Figure 1: Original field (left), reconstructed fields with $N = 10$ (center) and $N = 1000$ (right)

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